

# COLLABORATIVE ROBOT

INTELLIGENCE CHANGES THE WORLD COLLABORATION CREATES THE FUTURE

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#### AUBO (BEIJING) ROBOTICS TECHNOLOGY CO., LTD

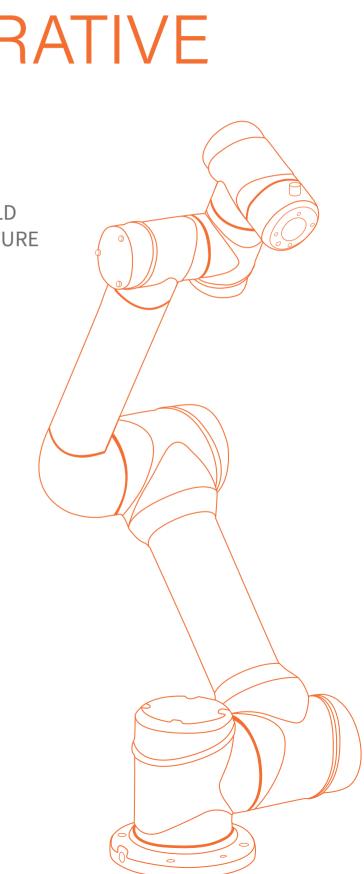
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#### COLLABORATION **CREATES THE FUTURE**



## **INTELLIGENCE CHANGES THE WORLD COLLABORATION CREATES THE FUTURE**

# **AUBO Brand**

Company Developm Qualificati



- Advantage
- i-series
- C-series
- Recomme
- Applicatio

## TABLE OF CONTENTS

Profile	P01
nent History	P03
ion Honor	P05

# **Products and solutions**

ges	P09
	P11
	P13
ended Industries	P15
on Cases	P17

#### **R&D and Production**

R&d and Innovation	P06
Production Capacity	P07
Product Guarantee	P08



Global Services

P23

# Determined to become an **outstanding collaborative robot**

enterprise in China and even the world

## 

#### **Provider of Collaborative Robots**

Established in 2015, AUBO Robotics is a national high-tech enterprise specialized in the research & development, production and sale of collaborative robots.

As a global leading provider of collaborative robots, AUBO has developed products with complete intellectual property rights, realizing full localization of core parts. AUBO collaborative robots have successively passed the certification of EN ISO 13849-1:2015(PL=d, CAT 3) , CE, UL, KCs, SEMI S2, etc. Featured by safety, stability and simple programming, the products are widely applied in the fields such as 3C, automobile, hardware and household appliances, sanitary appliances for kitchens and bathrooms, medical health, scientific research and education, catering, new retail, chemical products for daily use, and logistics.

Looking forward to the future, with the body of collaborative robots as the core and ecological products as the link, AUBO will provide customers with "plug and play" one-stop solutions, build an ecological innovation system of the robot industry, and collaborate the upstream and downstream enterprises to boost the development of the collaborative robot industry.











Localization of core parts



One-stop collaborative robot ecosystem

INTELLIGENCE CHANGES THE WORLD

COLLABORATION CREATES THE FUTURE

#### DEVELOPMENT HISTORY

#### 2010 **Commencement of R&D** The research and development of AUBO collaborative robot

commenced

Start-up

2012 **Establishment of a R&D** 

Center

Established a R&D center for independent research and development

## 2014

Dev

qol

The team was formally established

The professional team was formally established

## 2016

#### Putting into production

Jiangsu Changzhou Production Base was put into production

AUBO was approved to be National High-Tech Enterprise AUBO-i5 collaborative robots were produced in batches

The angel round investment of RMB60 million was obtained Subsidiaries in the USA, Germany, and offices in Shenzhen and Shanghai were established

## 2018

The first enterprise in China to pass (PL=d, CAT 3) security certification

The first enterprise in China to pass the security certification of EN ISO 13849-1:2015(PL= D, CAT 3) in the field of collaborative robot industry Approved National High-end Equipment Manufacturing Standardized Enterprise

## 2020

Building The domestic first intelligent and flexible production line of collaborative robots was released

The first massage robot was released in China

#### 2011

Appearance of conceptual machine

The conceptual machine of AUBO collaborative robot appeared

#### 2013 Debut of the first-generation product The first-generation AUBO

collaborative robots appeared

## 2015

#### **Establishment of the Chinese company**

AUBO (Beijing) Robotics Technology Co., Ltd. was established

AUBO-i5 collaborative robot was launched globally

## 2017

#### Academician Ni Guangnan as the chief scientist of AUBO

Round-A financing of RMB60 million was obtained

New collaborative robots i3, i7 and i10 were launched globally

The products passed the certification of CE, UL, KCs

## 2019

the ecosystem

#### Undertaking of projects under the National Key R&D Program

The "Working Group on Collaborative Robots of National Standard Commission" was established

Two "intelligent robot" projects under the National Key R&D Program were undertaken

AUBO i16, iV series collaborative robots were launched globally





#### AUBO

#### 2022

#### AUBO i20 collaborative robots was launched globally

AUBO i20 collaborative robots was launched globally

#### 2021 Sales exceeded 10,000 units

Sales exceeded 10,000 units Products passed SEMI S2 certification





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## Intellectual Property

(as at the date of March 2022)

#### 100



Effectively authorized patents

**35** Authorized patents for inventions

## **58**

Authorized patents for utility models

**42** Software copyrights

7

Appearance patents

- As a pioneer in the field of collaborative robot, AUBO has always focused on the needs in the field of collaborative robots, constantly improved its ability of innovation, promoted the application of scientific research results, and won a number of honors.
- National High-Tech Enterprise
- The best-selling cobot of the year (2017/2018/2019/2020/2021) in China\*
- IEEE Global Most Potential Collaborative Robot Enterprise
- The First Prize of Award for Scientific and Technological Progress in Machinery Industry
- National Pilot Unit for Standardization of High-End Equipment Manufacturing Industry (2/98)
- Drafting Unit of National Standard for Collaborative Robots (GB/T36008-2018)
- Secretariat Unit of the Working Group on Collaborative Robots of the National Automation Standards Commission
- Member of Expert Group on the International Standard for Robot Modularization ISO-TC299/WG10



#### R&D AND INNOVATION

Technical innovation is the core competitiveness of the enterprise. AUBO has always followed the road of being independent and controllable, and R&D and innovation. It has built an excellent technical innovation team, and established a normative product development process system. At present, more than 70% of team members are medium- and high-level technical and management talents.



#### Setter of National Standard for Collaborative Robots

Relying on outstanding strength in technical R&D and distinctive status in the industry, AUBO has participated in the formulation of 21 national and industrial standards for robots, including 3 national standards it organized to formulate. AUBO has undertaken 6 projects under the National Key R&D Program, including 2 projects it organized to declare.

#### Titles of national standards it organized to formulate

«Design Specification of Industrial Robots for Human-Computer Collaboration» GB/T 39402-2020

«Universal Module Interface for Industrial Robots» GB/T 38560-2020

 $\langle\!\!\!\langle Code \text{ for Detection of Multidimensional Force / Torque Sensor for Robot}\rangle\!\!\rangle$  20203656-T-604

#### Names of projects under the National Key Research & Development Program it organized to declare

«R&D and Integration Verification of Integrated Joints for Collaborative Robots»

«Application Demonstration of Collaborative Robot System for Typical Auto Parts Assembly»



05 / 06

#### Ni, Guangnan Chief Scientist

Academician of Chinese Academy of Engineering

#### Wei, Hongxing Chairman

Member of the Institute of Electrical and Electronic Engineers (IEEE) Member of Association for Computing Machinery (ACM) Member of National Subcommittee for Robots and Robotic Devices Head of Working Group on National Standards for Robot Modularization Undertaken many projects in the field of robotics under National 863 and Natural Fund Programs Won 5 provincial and ministerial level awards and Beijing New Star in

Science and Technology

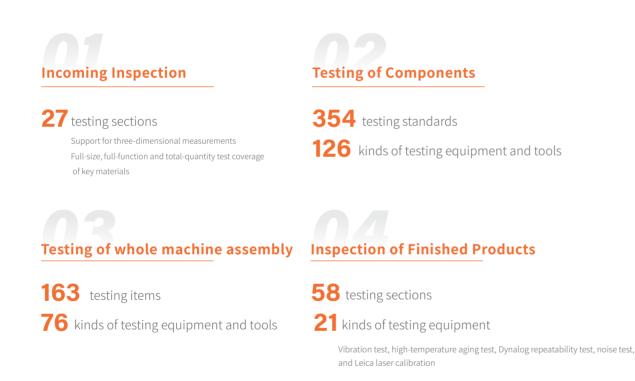
More than 100 papers, 2 monographs and 2 teaching materials



## **PRODUCTION CAPACITY**

AUBO Production Base is located in Changzhou City, covers an area of 12,000m<sup>2</sup>, and has an annual production capacity of 10,000 sets. In virtue of vertical integrated production capacity and complete supporting systems of the industry chain, AUBO can deliver high-quality products on schedule to meet customers' needs.

Production, process, quality, and supply chain integration of collaborative robots





Collaborative robots testing hall



The first intelligent and flexible production line of collaborative robots in China

#### PRODUCT GUARANTEE

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자용인전확인해보

AUBO is committed to providing safe and reliable collaborative robot products for customers. The products have passed the certification of EN ISO 13849-1:2015(PL=d, CAT 3), CE, UL, KCs, SEMI S2, etc., guaranteeing the safety and reliability of the products throughout the life cycle.

#### The First Enterprise Passing Security Certification of PL=d, CAT 3 in China











#### COLLABORATIVE ROBOT ADVANTAGES



#### **Flexible Deployment**

- Light, compact and small footprint.
- It takes only half a day in average to deploy the arm to execute new tasks.



#### **Simple Programming**

- It is available to master the programming method in half an hour, and complete simple programming in 1 hour.
- Dragging teaching and visualized programming to make the operation simple and efficient, you can operate robots easily without being proficient in programming language.



#### **Safety and Stability**

- The products have passed the certification of EN ISO 13849-1:2015(PL=d, CAT 3), CE, UL, KCs, SEMI S2, etc.
- Level-10 collision detection and sensor safety testing are supported.
- The terminal does not drop in case of power failure, so the products are safe and stable.
- 16 safe I/O interfaces are provided, so the safety function does not lose in case of single failure.



#### Modularization

- It's available to realize fast dismantlement and replacement within 15 minutes.
- The repair and maintenance are quicker and more convenient.



#### **High Precision**

- Millisecond-level system response ensures repeatability.
- The repeatability can be up to  $\pm 0.02$  mm.







#### **Flexible Production**

• With quick changeover of multiple function scenarios, human-machine collaboration, dual-machine collaboration and multi-machine collaboration, etc. can be adopted to realize flexible production.



#### **Wide Application**

• The products have been applied in batches in the fields such as 3C, automobile, hardware and household appliances, sanitary appliances for kitchens and bathrooms, medical health, scientific research and education, catering, new retail, chemical products for daily use, and logistics.



#### **System Opening**

- Connection of multi-language environments, multiple communication protocols, and deep integration with third-party plug-ins.
- Communication protocols: TCP/IP, Modbus-RTU/TCP, Profinet.
- Interface and openness: SDK (supporting the development of C/C++/C#/Lua/Python), API.
- Supporting Linux, Windows and Robot Operating System (ROS).



#### **High Return on Investment**

- Key and core components are 100% manufactured in China.
- The investment cost can be recovered within 6~12 months on average.

SERIES "	
COLLABORATIVE	
ROBOT	

AUBO i series collaborative robots with payload capacity of 3 to 20KG, which can cover different applications in each industry, and quickly adapt to the needs of application scenarios in various industries by means of abundant configuration options. They are ideal choices for improving the production efficiency and implementing the low-cost operation.

#### FEATURES AND **BENEFITS**

- Safer The products have passed the certification of EN ISO 01 13849-1:2015(PL=d, CAT 3), CE, UL, KCs, SEMI S2, etc., all core parts are localized, and level-10 collision detection and sensor safety testing are supported, so no safety protection is required.
- **More open** The open system platform supports multiple communica-02 tion methods:SDK and API, and can establish communication with multiple peripheral equipment such as end-of-arm tooling, vision and mobile robots.
- **More precise** With repeatability of  $\pm 0.02$  mm, high-precision work 03 can be completed continuously for a long time, thus greatly enhancing the production yield.
- **Simpler** Robots can be operated by many methods including dragging 04 teaching, coordinate positioning, path planning and offline programming. The visual interface is simple and easy to learn.
- Wider The whole series products with payload capacity of 3 to 20KG, 05 which can cover different applications in each industry and have a wide range of applications.

## Applicable Fields

3C, automobile, hardware and household appliances, sanitary appliances for kitchens and bathrooms, medical health, scientific research and education, catering, new retail, chemical products for daily use, and logistics.



#### AUBO-i3

Payload:3kg Weight:16kg Repeatability: ±0.02mm Reach:625mm

#### AUBO-i5/i7

Payload:5kg/7kg Weight:24kg Repeatability: ±0.02mm Reach:886.5mm/786.5mm

#### AUBO-i10/i12

Payload:10kg/12kg Weight: 38.5kg/40kg Repeatability: ±0.03mm Reach:1350mm/1250mm

#### AUBO-i16

Payload:16kg Weight:38kg Repeatability: ±0.03mm Reach:967.5mm





Payload:20kg Weight:63kg Repeatability: ±0.1mm Reach:1650mm

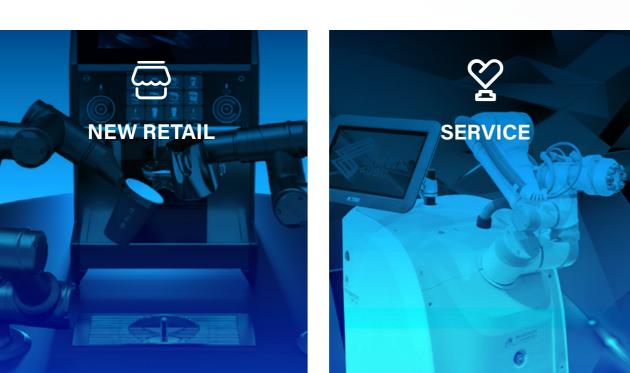


Aubo C series collaborative robots are developed based on the application characteristics of the industries such as service and new retail. The products have payload capacity of 3KG and 5KG, which can meet the needs in the fields of service and new retail, and have an extremely high return on investment.

# FEATURES AND **BENEFITS**

- Low cost input, high return on investment, and payback period of 3 to 9 months averagely
- Small footprint and fast deployment, suitable for installation in narrow spaces
- Super-simple workflow graphic interface, rich and friendly script programming to achieve quick and skilled operation
- Modular design of integrated joints, convenient disassembly and installation, and higher maintenance efficiency
- Small changes to the surrounding environment to achieve high-efficiency and low-cost operation
- Standardized intelligent interface, open programming language, and extremely high extendibility
- Independent collocation of different accessories to achieve rich and diverse functions

## Applicable Fields







Payload:3kg Weight:16kg Repeatability:±0.1mm Reach:625mm



AUBO

#### AUBO-C5

Payload:5kg Weight:24kg Repeatability: ±0.1mm Reach:886.5mm

## INDUSTRIES

AUBO collaborative robots are designed for a variety of industrial processes and can be operated with simple training.

Others



Automobile

TYPICAL PROCESS

<del>لم</del> **Chemical Products** for Daily Use

5

Logistics

iM

**Scientific Research** and Education

New Retail

#### Hardware and Household Machining Appliances Ų Catering **Medical Health** (···)



**Kitchens and Bathrooms** 







CASES

3D Scanning and inspection

Inspection of parts





Inspection of circuit boards

Instrument assembly





Intelligent assembly of auto parts

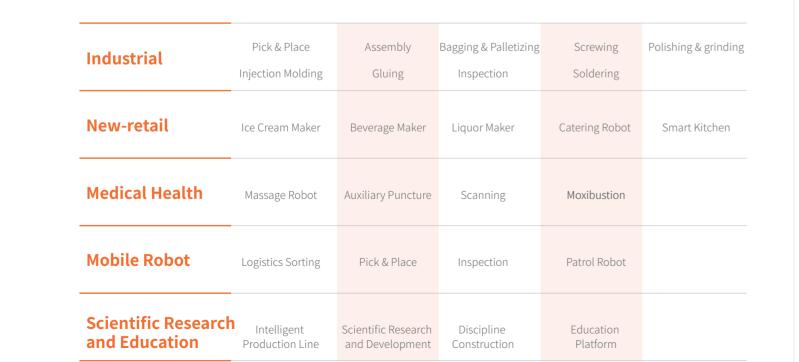
Welding





Vacuum cup stretching line

Frame coating



#### 15 / 16

AUBO

#### INDUSTRIAL **FIELD**





mobile phone camera detection



Appearance inspection of auto parts



Assembly and screwing of white household appliances



Gluing of vehicle windows



Machine Tending



Rubber assembly of auto electronic control systems



Stacking of packing boxes



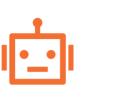
Machine Tending



#### **NEW RETAIL / SERVICES**



**HEALTHCARE** 



**MOBILE COBOT** 



#### **RESEARCH AND EDUCATION**



**OTHER FIELDS** 



Latte art robot



Smart restaurant



Milk tea workstation



Massage robot



Tooth implantation robot



Reagent testing



Inspection robot



Intelligent archives



5G Patrol robot



Robot with digital twin technology



Music box assembly line



Education and training platform









High-voltage distribution cabinet operation



Hygiene & cleaning

## APPLICATION CASES

#### Automobile

#### **Automobile Glass Gluing & Sealing**

This is the window glass gluing & sealing project customized for a well-known automobile company. Industrial robots or manual gluing is adopted on the traditional production lines. Due to safety restrictions, traditional industrial robots need to be separated from workers by guardrails, and the utilization rate of the production line is limited. It is difficult for manual gluing to control the accuracy and quality.

Quick deployment and small footprint with human-machine collaboration. Uniform gluing speed and glue type control precision of  $\pm$ 0.5mm.

#### **Continuous Efficient Operation**

Since being put into use in August 2019, the cobot has been running efficiently in good condition for 16 hours a day, and can completely replace manual labor.



## Automobile

#### **Engine Screwing**

This is the engine assembly line renovation project of a well-known automobile company. Previously, the screw locking operation was mainly completed by manual labor. Manual operation is labor-intensive, assembly quality is not consistent enough, and it is difficult to improve the yield of finished products. The workshop space is relatively narrow, and the volume and freedom are highly limited. In addition, the screwing has a fixed sequence, the screws are divided into 5 categories and more than 100 sub-models, requiring visual identification of common features. Precise screw torque and

high positioning repeatability are required.

The terminal screwing device adopts a screw gun with controllable torque, and it has compact structure and high torque control accuracy. The "eye-to-hand" vision system is selected, and the vision sensor is independently fixed on the bracket to ensure high positioning repeatability.



#### **Reduced Manpower and Increased Productivity**

Since operation in April 2019, the production efficiency has been increased by 18%, the product yield has been increased by 12%, the number of personnel has been reduced by 50%, and the labor cost has been reduced by 30%.

#### Mobile Phone Camera Testing

This is the camera function testing process of a well-known mobile phone manufacturer. Previously, the testing operation was performed by manual labor. The testing environment is divided into indoor and outdoor, and a variety of products, statuses and angles are involved, which are difficult to control for manual labor. The testing is cumbersome and labor-intensive, needs long continuous operation time.

AUBO adopts the mobile cobot solution (AGV + collaborative robot) to work in the live-action studio according to the specified shooting angles.

#### **Stable and Efficient**

24-hour operation is possible, and more comparative data can be captured in the same time period, so the efficiency is significantly improved.

#### Machining

#### **Machine Tending**

This is the machining production line renovation project of a well-known company. The company mainly produces precision machinery parts, such as various industrial sewing machine parts, power tool parts and auto parts. With the growth of business volume, manual operation can no longer meet the production demands.

There are a wide range of products, and one person can only handle 2 machines for original production equipment, cannot accurately complete all tasks. Problems such as on-site environment and equipment noise have led to a series of common problems in traditional manufacturing industry, such as labor shortage and increasing labor cost.

#### **Flexible Deployment**

The reach of the collaborative robot used in this solution can be up to 1350mm, and the customer can directly deploy on the original factory without changing the layout of the production line. Flexible pick & place of parts is achieved in the narrow working space, and one robot is working for 2 machines. In the original production process, one person can operate up to 2 machines at the same time. After the deployment of collaborative robots, two persons can handle 12 machines at the same time. In this way, the production scale has tripled, while the personnel have not undergone major changes.

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# APPLICATION CASES

## **Medical Health**

#### Massage Robot

Traditional Chinese Medical Massage has always been one of the first choices for people to carry out cervical and lumbar care or pain management. But the shortage of professional massagist has been a major problem in the industry. AUBO developed the massage therapy robot together with our partner, committed to proving safe, temperature-controlled, efficient and standard services in the full process of massage.

The end of the cobot is equipped with a force sensor, a 3D vision, a massage head and a thermal imaging, when the robot arm walks the massage track on the human body, it can ensure the safe and stable operation of the robot without hurting the human body accidentally. And there are different types of strengths that can be switched automatically during the massage according to customers' force preference.

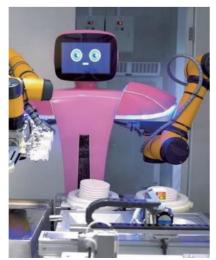


#### **New-retail**

#### **Dual-Arm Hamburger Robot**

In smart catering industry, AUBO has started business operation officially by cooperating with many restaurants at present. In addition to hamburger robots, the application of robots in restaurants includes stir-fry robots, soup rice robots, drinks robots, frying robots, dessert robots and meals-delivery robots, etc.

In this case, two sets of AUBO i3 cobots are installed inversely, which can be compatible with two collaborative robots to make hamburgers at the same time. After a customer places an order by scanning the QR code, the upper computer sends a signal to the cobots to start the making of hamburger. One cobot mainly grabs bread pieces from the material silo and sends them to the heating furnace, and cooperates with the sauce machine to pour the sauce onto the heated bread pieces; the other cobot takes vegetables and returns the tray. Then, the cobots complete the combination of the upper and lower pieces of bread. After packing, the cobot places the packed hamburger onto the conveyor belt. The customer can scan the QR code to open the pickup window. Here, the purchase process is completed.



## **Mobile Robot**

#### Semiconductor Handling

This is the logistics automation renovation project in the packaging and testing workshop of a semiconductor industry. At present, the industry is mainly based on manual labor. Manual handling has problems such as large vibration, being easy to cause particle pollution, discontinuous operation, wrong handling and poor consistency. The workshop has a high level of cleanliness, a complex layout, a narrow space and a wide variety of equipment with discrete production processes and complex technological processes. The industry order demands are flexible, and it is impossible to form a simple and effective flow-line production.

The mobile cobot and the intelligent dispatching logistics control system help the factory realize an intelligent unmanned production workshop. The mobile cobot is based on the hybrid positioning and natural navigation technology of the laser natural navigation. The indoor positioning repeatability of  $\pm$ 5mm can be achieved without environment modification while the dust-free operation meets the standard. Equipped with a 360°-scanning dual safety lidar, obstacles can be identified intelligently and avoided actively, ensuring safe, high-speed and smooth operation. Target positions such as cartridge holder and tray can be positioned and captured accurately through AI algorithm, 3D visual positioning, force sensor and collaborative robot.

#### 24-hour Operation and Labor Liberation

The solution realizes the die bond among various processes, and 24-hour continuous operation is possible so as to liberate labor, solve information flow conversion, and realize workshop production visualization and production process operation control.

## **Electric Power Industry**

#### **Distribution Room Inspection**

This is the automatic distribution room inspection project of a power industry user. At present, the industry is mainly based on manual inspection. The automation equipment in the distribution room operates all the year round, so the failure rate is high. The inspection frequency is high, the work is cumbersome, and the manual inspection burden is heavy. The switch on the low-voltage side of the distribution room cannot be remotely controlled, and automation cannot be achieved through the equipment in the cabinet.

In cooperation with China Unicom, a dedicated 5G channel ensures safe and stable operation of the robots. The big data image recognition intelligently distinguishes equipment fault signals, and provides intelligent safety monitoring for the robot manipulation equipment to prevent misoperation and faults. The inspection robot can independently complete more than ten functions such as equipment inspection, device panel control, faulty part replacement, device restart, and switch opening & closing. The historical alarm records in the device can be viewed to make up for the shortcomings of the inability to collect alarm information when the equipment in the station malfunctions.

#### **Unmanned Operation**

The inspection robot has the characteristics of low cost, high reliability, high safety and strong universality, and can be maturely applied to most scenarios in which unmanned equipment operation is required, such as distribution rooms, computer rooms and industrial enterprises.

21 / 22

AUBO





## GLOBAL SERVICES

Around the global headquarters and manufacturing bases, AUBO has established sales centers in the eastern region, southern region and northern region, etc. of China, and overseas after-sales service centers in the USA and Germany, etc. Now, AUBO has more than 200 distributor partners from more than 50 countries in the world, and can provide efficient and convenient professional services for you.



To provide technology evaluation, accessory selection and debugging services.



To provide product usage trainings to distributors free of charge regularly, and cultivate professional robot engineers for customers.



To realize real-time technology answers and resource sharing by technical forum and hotline.

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23 / 24

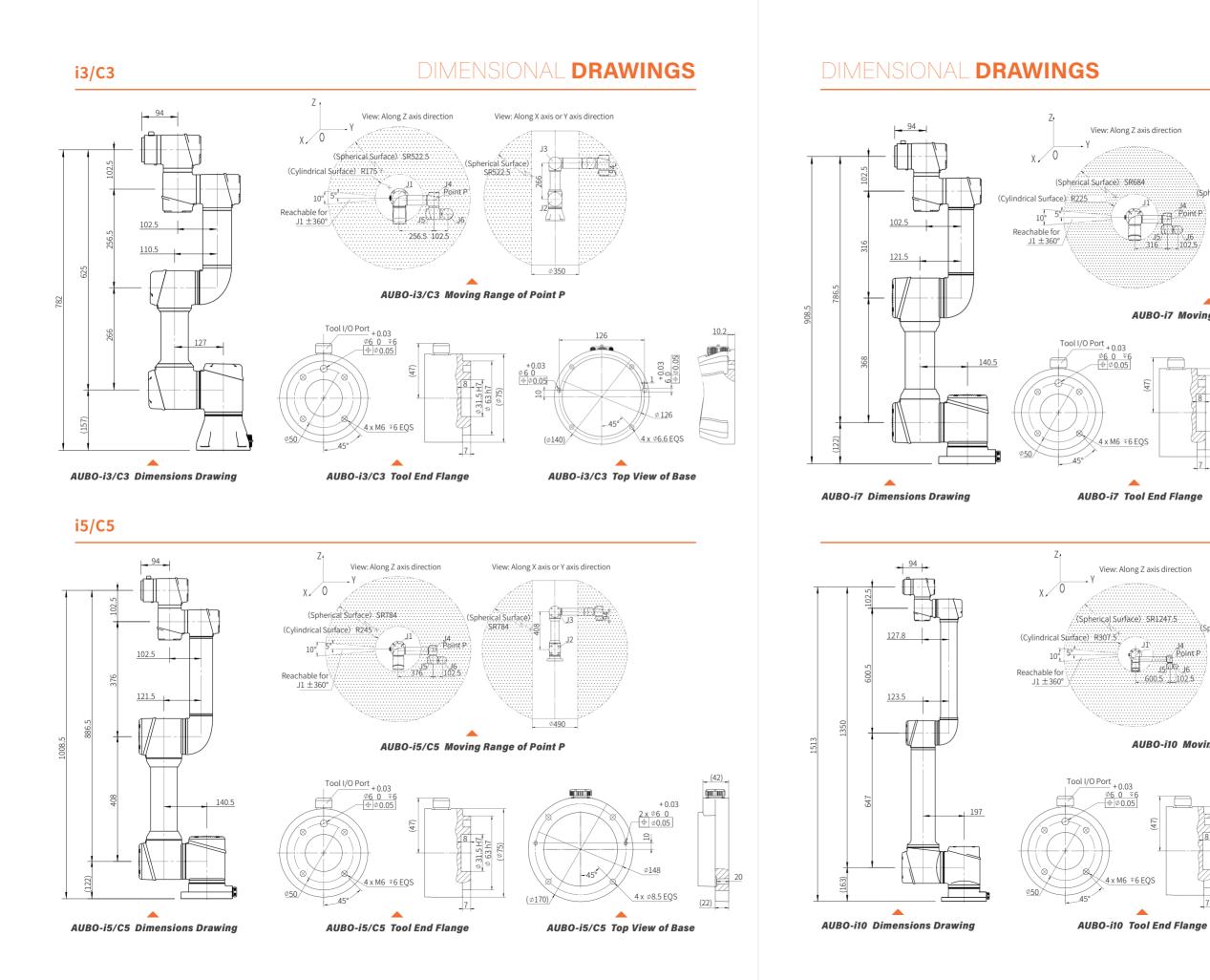
AUBO

To provide lifetime repair and customized maintenance of robots, and provide software upgrading package to customers and instruct them how to install.

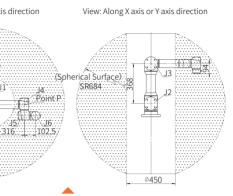


																		25 / 26	AUBO
	Model		i3		i5		i7	i1	LO	i	12	i	16	i2(	0	C	:3	C5	
Robot	Degrees of Freedom		6		6		6	6			6	6		6	6		6	6	
	Weight (kg)		16		24		24	38.5			40		38	63	}	6.	25	886.5	
	Reach (mm)		625	8	86.5		786.5	13	350	1	250	9	67.5	165	50		3	5	
	Mounting Surface Diameter (mm)	) (	Ø140	Q	0172		Ø172	Ø2	220	Ø	220	Ø	0220	Ø26	60	1	.6	24	
	Payload (kg)		3		5		7	1	.0		12		16	20	)	Øl	40	Ø172	
	Repeatability (mm)	±	±0.02	+	:0.02	:	±0.02	±(	0.03	±	0.03	±	:0.03	±0	.1	±	0.1	±0.1	
	Linear Velocity (m/s)	\$	≤1.9	\$	≤3.4		≤3.0	\$	4.0	\$	3.8	\$	≤3.0	≤2	.6	\$	1.9	≤2.8	
	Average Power (W)		150		200		200	5	00	3	500	(	600	100	00	1	50	200	
	Peak Power (W)	1000		2	2000	2000		20	000	2000 2000		2000	3000		600		600		
	Ambient Temperature (°)	) 0-50		0-50		0-50		0-	0-50		0-50		0-50		0-50		0-50		
	Ambient Humidity	Ambient Humidity 90% RH (Non-condensing)		90% RH (Nc	on-condensing)	90% RH (Non-condensing)		90% RH (Non-condensing)		90% RH (Non-condensing)		90% RH (Non-condensing)		90% RH (Non-condensing)		90% RH (Non-condensing)		90% RH (Non-condensing)	
	Installation Orientation	Any ceilir	ng, Floor, Wall	Any ceilin	g, Floor, Wall	Any ceili	ng, Floor, Wall	Any ceiling	, Floor, Wall	Any ceiling	g, Floor, Wall	Any ceilin	g, Floor, Wall	Any ceiling,	Floor, Wall	Any ceiling	, Floor, Wall	Any ceiling, Floo	r, Wall
	IP Classification		IP54	IP54		IP54		IP54		IF	P54	1	P54	IP5	64	IP	54	IP54	
	Axis Movement	Working Range (°)	Maximum Speed (°/s)	Working Range (°)	Maximum Speed (°/s)	Working Range (°)	Maximum Speed (°/s)	/s) Working Range (°) Maximum Speed (°/s)		Working Range (°) Maximum Speed (°/s) Wo		Working Range (°) Maximum Speed (°/s) Work		Working Range (°) N	laximum Speed (°/s)	Working Range (°) Maximum Speed (°/s)		Working Range (°) Max	imum Speed (°/s)
	joint 1	±360	178	±360	223	±360	223	±360	178	±360	178	±360	178	±360	93	±175	178	±175	147
	joint 2	±360	178	±360	223	±360	223	±360	178	±360	178	±360	178	±360	93	±175	178	±175	147
	joint 3	±360	178	±360	223	±360	223	±360	223	±360	267	±360	267	±360	178	±175	178	±175	147
	joint 4	±360	237	±360	237	±360	237	±360	178	±360	178	±360	178	±360	178	±175	178	±175	178
	joint 5	±360	237	±360	237	±360	237	±360	237	±360	178	±360	178	±360	178	±175	178	±175	178
	joint 6	±360	237	±360	237	±360	237	±360	237	±360	178	±360	178	±360	178	±175	178	±175	178
	*Limited by the application scenar	io, part of the	joints may not ach	ieve $\pm 360^{\circ}$ .															
	Category		C	ontrol Box			Control Bo	ox (AGV)		Control I	Box I/O/Tool I/	0 <u></u> C	ontrol Box	Tool End					
Control Box	Model			AUBO-CB-M		AUBC	)-CB-AGV	AUBO-CB-	AGV-P	I/O Port	Digital In	16 (g	general) /16 (safe)	4 (optional)	Теа	ich Pendant	Model	AUBO-TP	AUBO-TP-C
	Dimensions	390mm*370mm*265mm/410mm*390mm*285mm(i20)		370mm*295mm*225mm 357mm*200mm*207mm			Digital Out 16 (general) /16 (safe)			4 (optional) Dimension				ns 355mm*235mm*54mm					

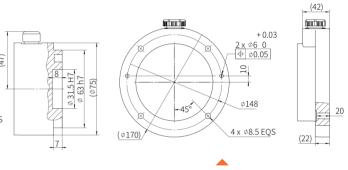
	Category	Control Box	Control E	Box (AGV)	Control	sox 1/0/10011/0	Control Box	lool End					
Control Box	Model	AUBO-CB-M	AUBO-CB-AGV	AUBO-CB-AGV-P	I/O Port	Digital In	16 (general) /16 (safe)	4 (optional)	Teach Pendant	Model	AUBO-TP	AUBO-TP-C	
	Dimensions	390mm*370mm*265mm/410mm*390mm*285mm (i20)	370mm*295mm*225mm	357mm*200mm*207mm		Digital Out	16 (general) /16 (safe)	4 (optional)		Dimensions	355mm*2	35mm*54mm	
	Weight	15kg/16kg (i20)	10.5kg	8.75kg		Analog In	4	2		Weight	1.	57kg	
	Cabling Connecting the Robot	5m (customizable,up to 8m)	5m	-		Analog Out	4	-		IP Classification	I	P43	
	Cabling Connecting the Teach Pendant	4m	4m	-	I/O Power	Output Voltage	24V	0V/12V/24V		Colour	Orange + Black	Blue + White	
	Cabling Connecting the Power	5m	5m	-		Output Current	3A Max	0.8A	Teach Pendant				
	Cabling Connecting AGV Control Box and	AGV Power Box -	-	0.65m									
	Communication	100-240VAC,50-6	0Hz	100-240VAC,50-60Hz									
	Interface	Ethernet、ModBus-RTU/TCP、P	rofinet (Optional)										
	Power Supply	SDK (Support C/C++/C#/Lua/Pytho	on) 、Support ROS、API					TECH	CHNICAL DETAILS COMPARISON				
	IP Classification	IP43					6						
				AUBO-CB-M	AUBO-CB-AG	AUBO-CB-	-AGV-P						







AUBO-i7 Moving Range of Point P

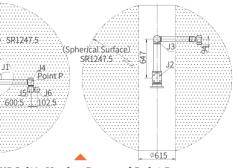


AUBO-i7 Top View of Base

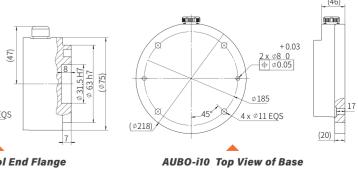
i10

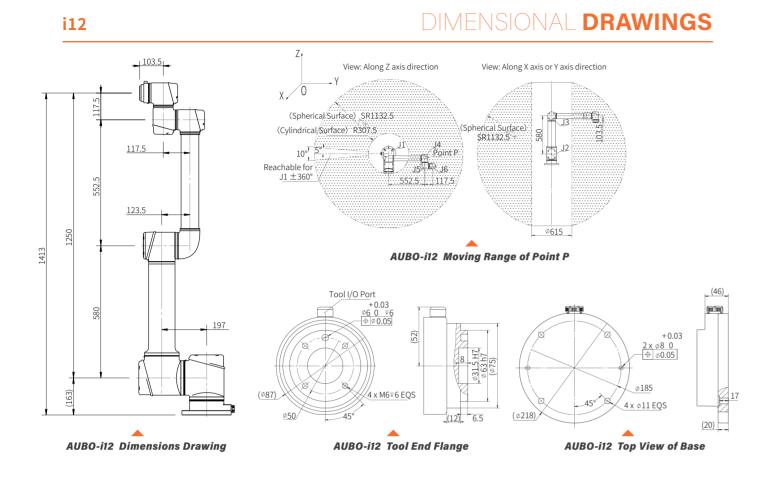


View: Along X axis or Y axis direction

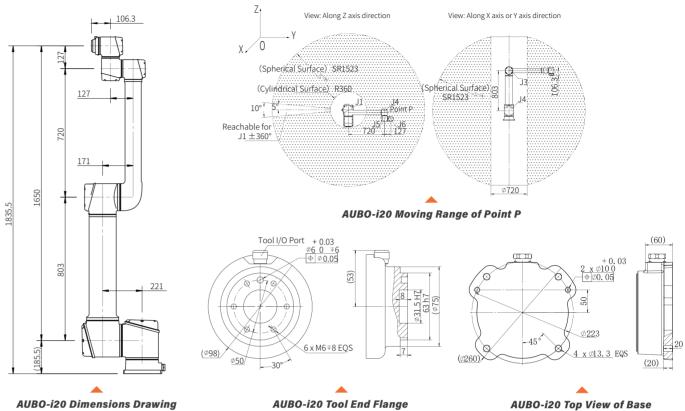




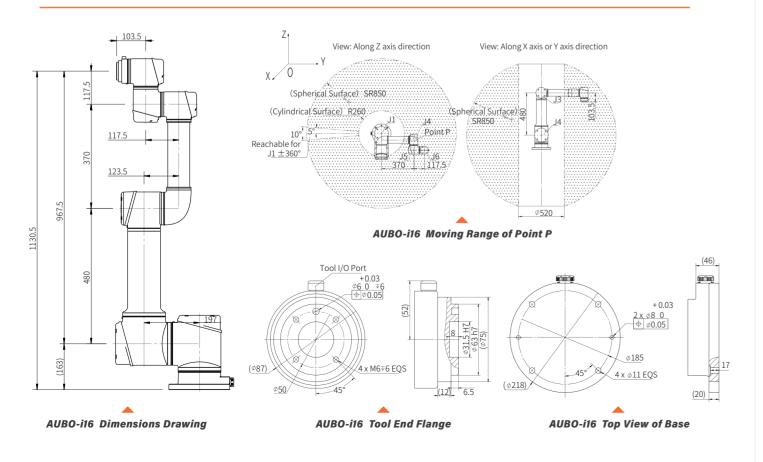




#### DIMENSIONAL DRAWINGS



i16



#### **29 / 30** AUBO

i20